

# Oblivious Routing and Minimum Bisection

## Seminar: Approximation Algorithms

Markus Kaiser

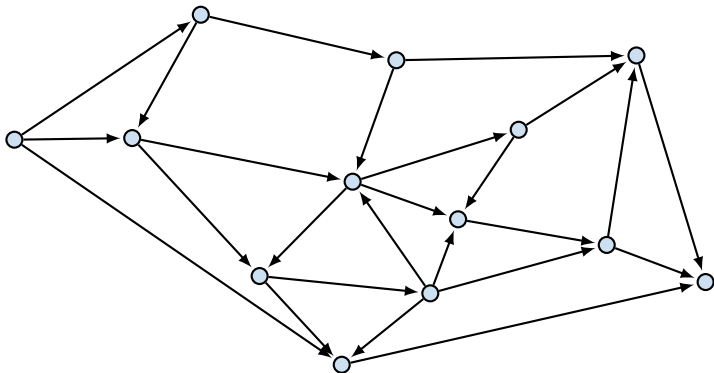
June 3, 2014

## Problem (Single Commodity Flow)

Given

- An (un)directed Graph  $G = (V, E)$
- A capacity function  $c : E \rightarrow \mathbb{R}^+$
- A source  $s$  and a target  $t$

Calculate a maximum possible flow  $f : E \rightarrow \mathbb{R}^+$  through  $G$ .

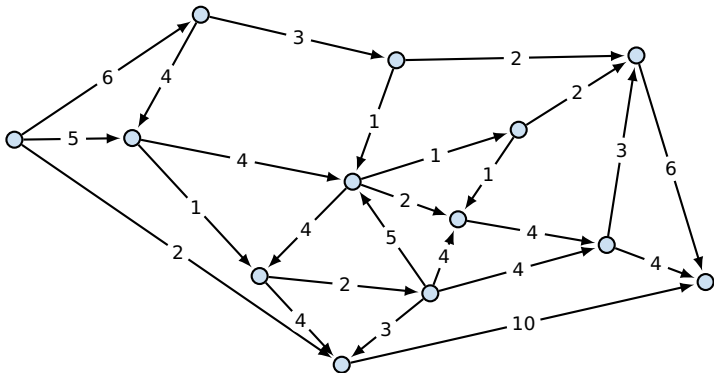


## Problem (Single Commodity Flow)

Given

- An (un)directed Graph  $G = (V, E)$
- A *capacity function*  $c : E \rightarrow \mathbb{R}^+$
- A source  $s$  and a target  $t$

Calculate a maximum possible flow  $f : E \rightarrow \mathbb{R}^+$  through  $G$ .

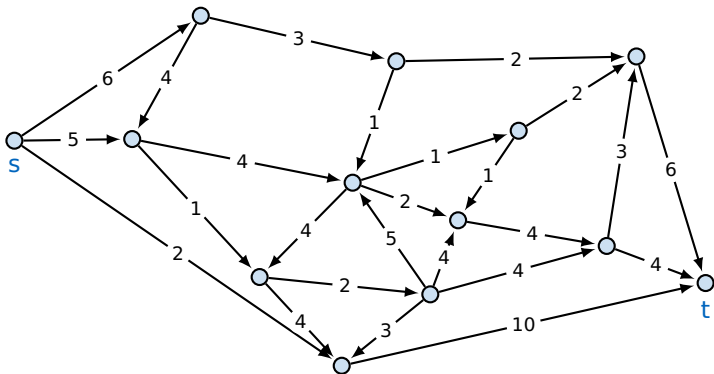


## Problem (Single Commodity Flow)

Given

- An (un)directed Graph  $G = (V, E)$
- A *capacity function*  $c : E \rightarrow \mathbb{R}^+$
- A source  $s$  and a target  $t$

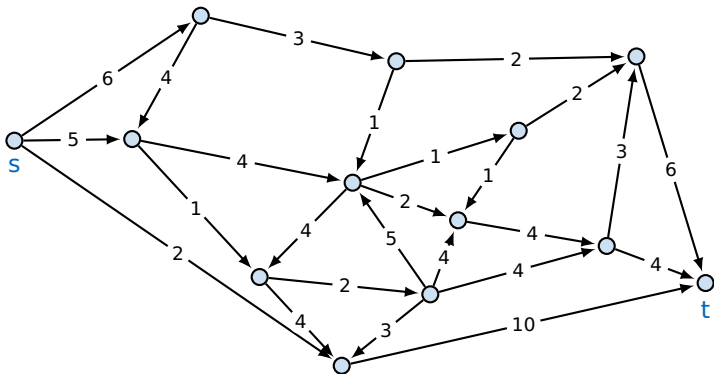
Calculate a maximum possible flow  $f : E \rightarrow \mathbb{R}^+$  through  $G$ .



## Problem (Single Commodity Flow)

Given

- An (un)directed Graph  $G = (V, E)$
- A *capacity function*  $c : E \rightarrow \mathbb{R}^+$
- A source  $s$  and a target  $t$

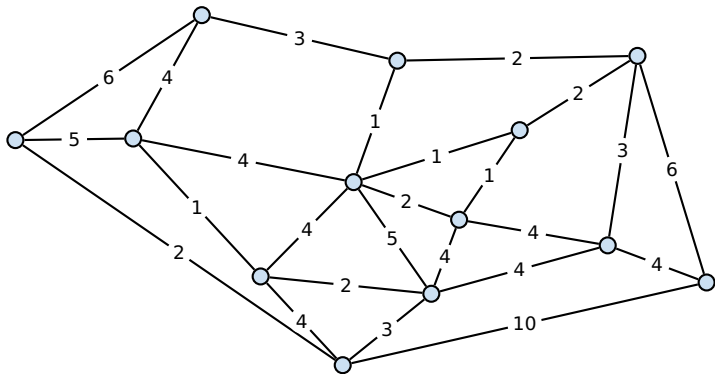
Calculate a maximum possible *flow*  $f : E \rightarrow \mathbb{R}^+$  through  $G$ .

## Problem (Multi Commodity Flow)

Given

- An undirected Graph  $G = (V, E)$
- A capacity function  $c : E \rightarrow \mathbb{R}^+$
- A demand function  $d : V^2 \rightarrow \mathbb{R}^+$

Calculate a flow  $f$  with least congestion  $\rho = \max_{e \in E} \frac{f_e}{c_e}$ .

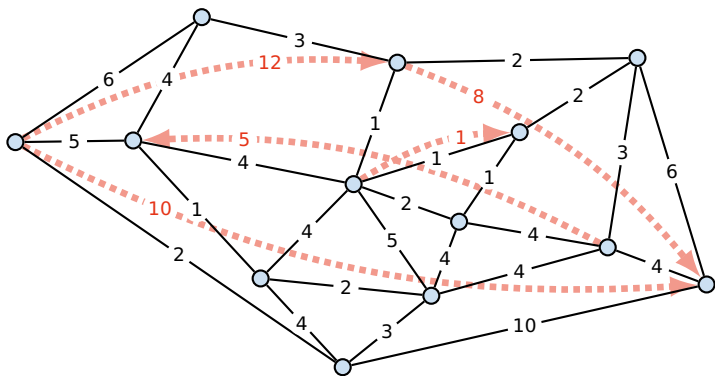


## Problem (Multi Commodity Flow)

Given

- An undirected Graph  $G = (V, E)$
- A capacity function  $c : E \rightarrow \mathbb{R}^+$
- A demand function  $d : V^2 \rightarrow \mathbb{R}^+$

Calculate a flow  $f$  with least congestion  $\rho = \max_{e \in E} \frac{f_e}{c_e}$ .

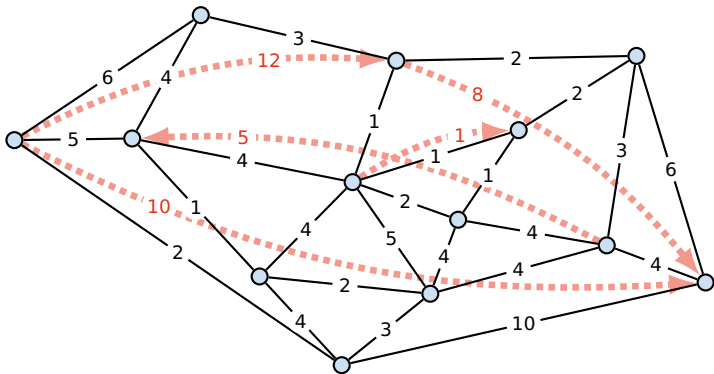


## Problem (Multi Commodity Flow)

Given

- An undirected Graph  $G = (V, E)$
- A capacity function  $c : E \rightarrow \mathbb{R}^+$
- A demand function  $d : V^2 \rightarrow \mathbb{R}^+$

Calculate a flow  $f$  with least congestion  $\rho = \max_{e \in E} \frac{f_e}{c_e}$ .



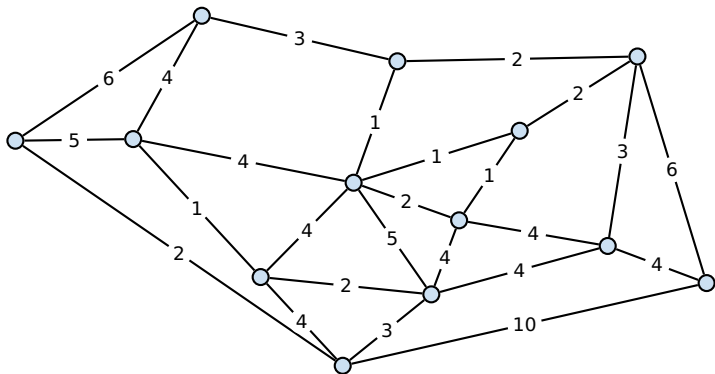


## Problem (Oblivious Routing)

Given

- An undirected Graph  $G = (V, E)$
- A capacity function  $c : E \rightarrow \mathbb{R}^+$

Calculate a combination of paths for each  $(u, v) \in V^2$  such that for **any** demand function the **congestion** will be as small as possible.

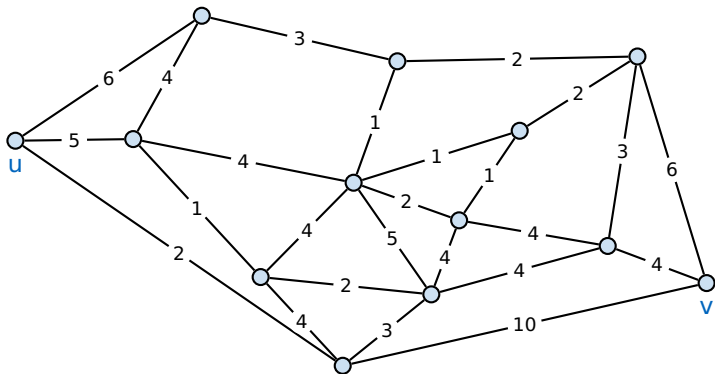


## Problem (Oblivious Routing)

Given

- An undirected Graph  $G = (V, E)$
- A capacity function  $c : E \rightarrow \mathbb{R}^+$

Calculate a combination of paths for each  $(u, v) \in V^2$  such that for **any** demand function the **congestion** will be as small as possible.

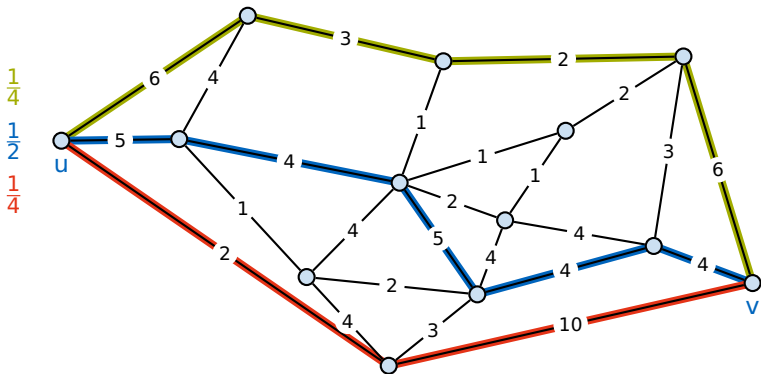


## Problem (Oblivious Routing)

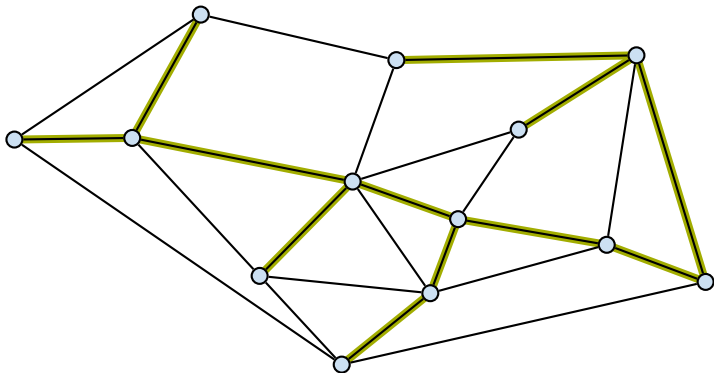
Given

- An undirected Graph  $G = (V, E)$
- A capacity function  $c : E \rightarrow \mathbb{R}^+$

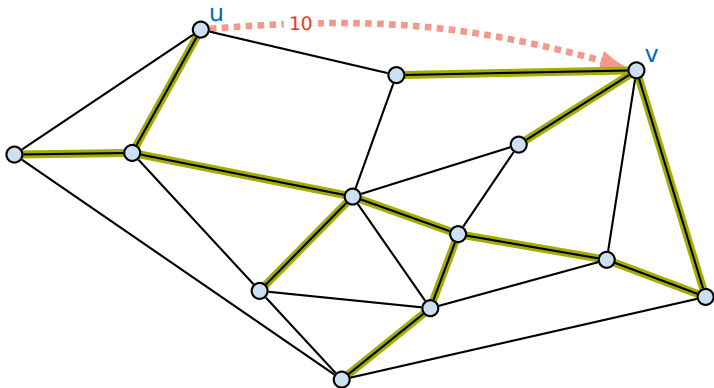
Calculate a combination of paths for each  $(u, v) \in V^2$  such that for *any* demand function the *congestion* will be as small as possible.



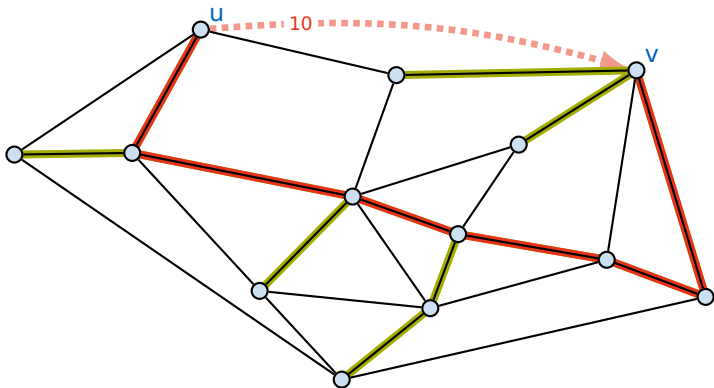
- Choose any **spanning tree**  $T$  of  $G$
- Routing along its unique paths is a feasible solution



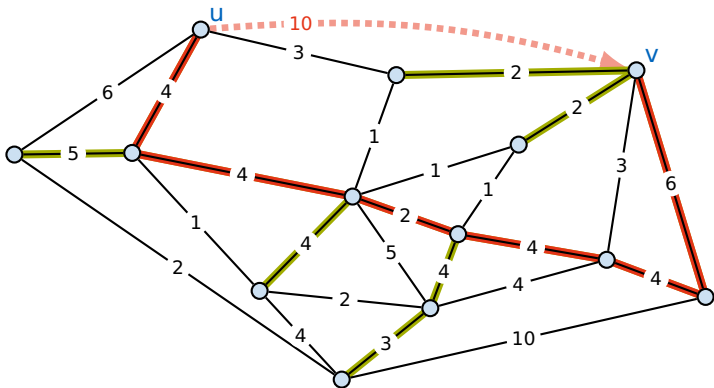
- Choose any **spanning tree**  $T$  of  $G$
- Routing along its unique paths is a feasible solution



- Choose any **spanning tree**  $T$  of  $G$
- Routing along its unique paths is a feasible solution



- Choose any **spanning tree**  $T$  of  $G$
- Routing along its unique paths is a feasible solution

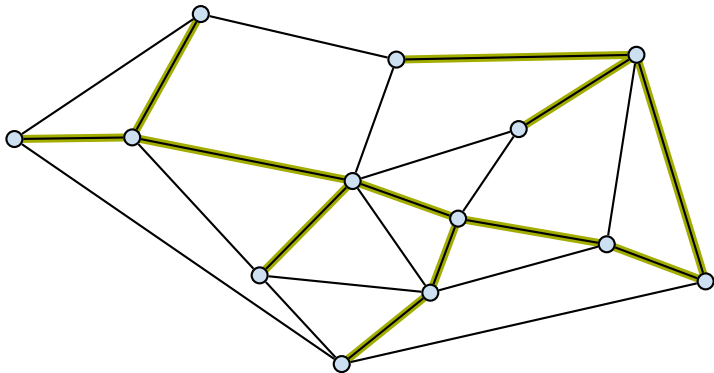


$$\rho = \max_{e \in E} \frac{f_e}{c_e} = \frac{10}{2} = 5$$

- Removing one edge  $e_T$  from a ST creates a **node partition**  $S(e_T)$
- Every such partition has a **capacity**  $C(e_T)$
- And a **demand**  $D(e_T)$

$$C(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$

$$D(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$

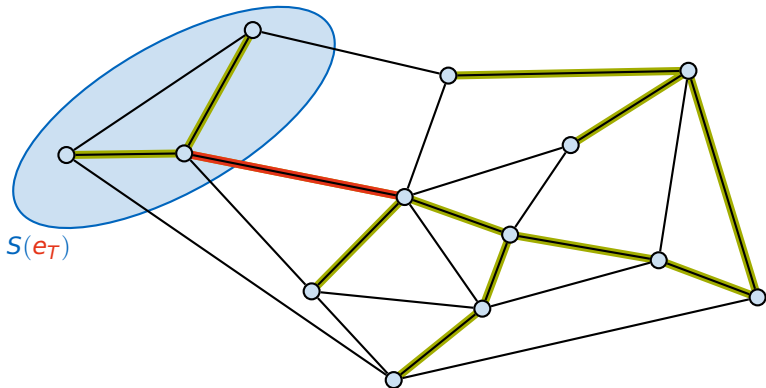




- Removing one edge  $e_T$  from a ST creates a **node partition**  $S(e_T)$
- Every such partition has a **capacity**  $C(e_T)$
- And a **demand**  $D(e_T)$

$$C(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$

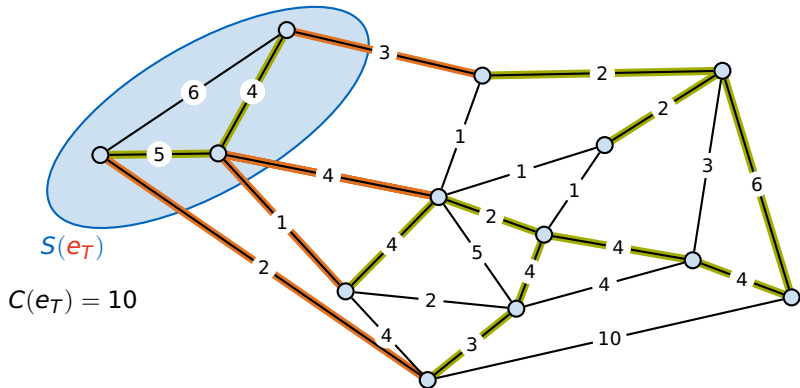
$$D(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$



- Removing one edge  $e_T$  from a ST creates a **node partition**  $S(e_T)$
- Every such partition has a **capacity**  $C(e_T)$
- And a **demand**  $D(e_T)$

$$C(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$

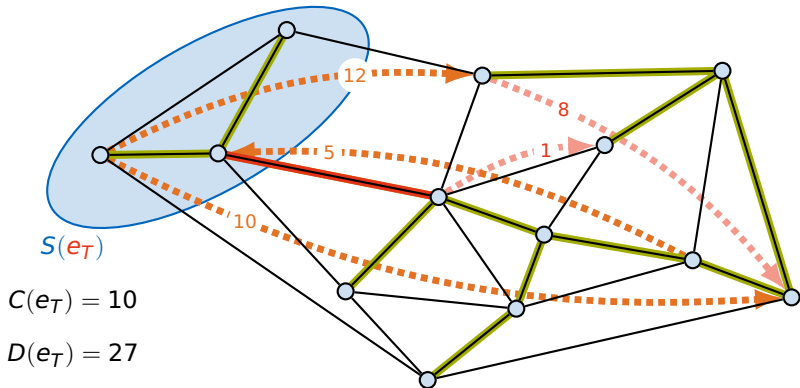
$$D(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$



- Removing one edge  $e_T$  from a ST creates a **node partition**  $S(e_T)$
- Every such partition has a **capacity**  $C(e_T)$
- And a **demand**  $D(e_T)$

$$C(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$

$$D(e_T) = \sum_{\substack{u \in S(e_T), \\ v \notin S(e_T)}} c_{uv}$$



## Lemma

For any tree  $T$  and any tree edge  $e_T$ , we know that for *any routing* in  $G$  there must be an edge with *congestion*

$$\rho_e \geq \frac{D(e_T)}{C(e_T)}$$

And therefore the *optimal solution*  $\rho^*$  can be no better.

- Suppose we find a tree such that for some  $\alpha$

$$\forall e_T \in E_T. \quad c_{e_T} \geq \frac{1}{\alpha} C(e_T)$$

- Then we have

$$\rho_T = \max_{e_T} \frac{D(e_T)}{c_{e_T}} \leq \alpha \max_{e_T} \frac{D(e_T)}{C(e_T)} \leq \alpha \rho^*$$

## Lemma

For any tree  $T$  and any tree edge  $e_T$ , we know that for *any routing* in  $G$  there must be an edge with *congestion*

$$\rho_e \geq \frac{D(e_T)}{C(e_T)}$$

And therefore the *optimal solution*  $\rho^*$  can be no better.

- Suppose we find a tree such that for some  $\alpha$

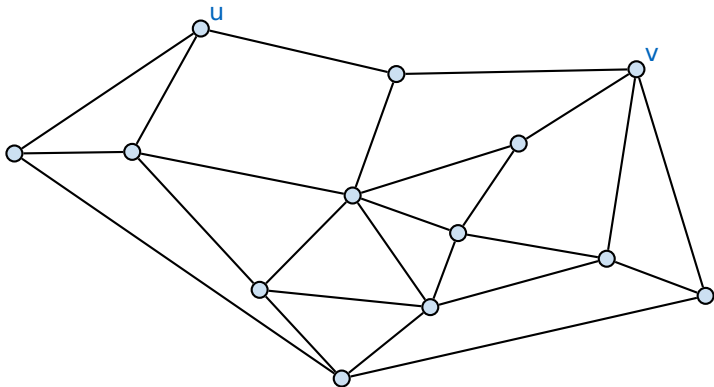
$$\forall e_T \in E_T. \quad c_{e_T} \geq \frac{1}{\alpha} C(e_T)$$

- Then we have

$$\rho_T = \max_{e_T} \frac{D(e_T)}{c_{e_T}} \leq \alpha \max_{e_T} \frac{D(e_T)}{C(e_T)} \leq \alpha \rho^*$$

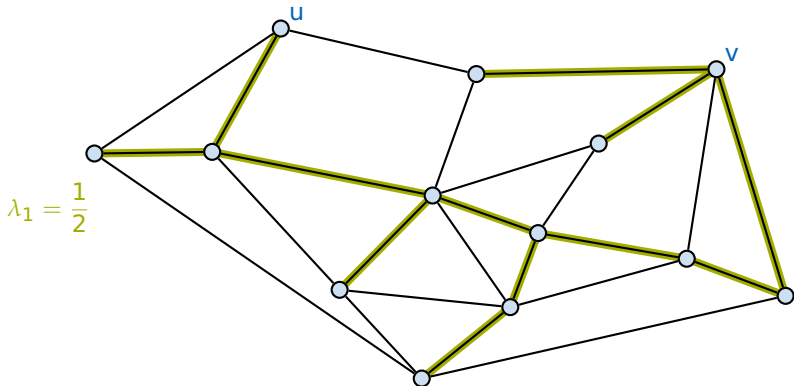
- Choose a set of spanning trees  $\{T_i\}$  of  $G$
- And a convex combination  $\lambda$  with  $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For  $e \in E$

$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$



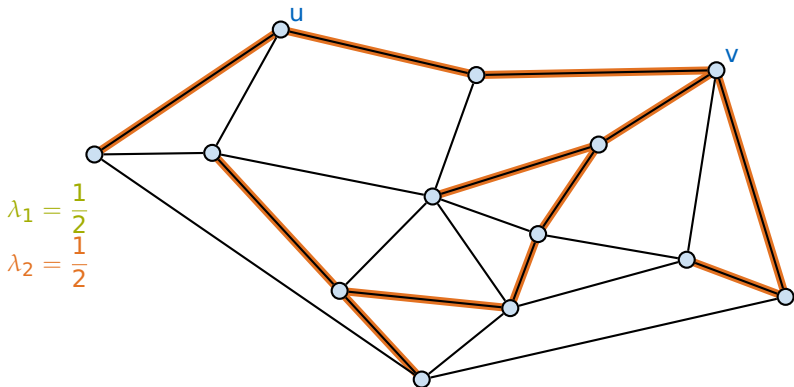
- Choose a set of spanning trees  $\{T_i\}$  of  $G$
- And a convex combination  $\lambda$  with  $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For  $e \in E$

$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$



- Choose a set of spanning trees  $\{T_i\}$  of  $G$
- And a convex combination  $\lambda$  with  $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For  $e \in E$

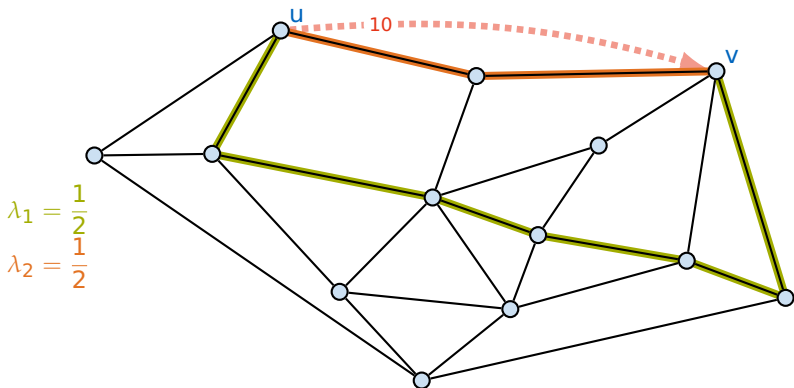
$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$





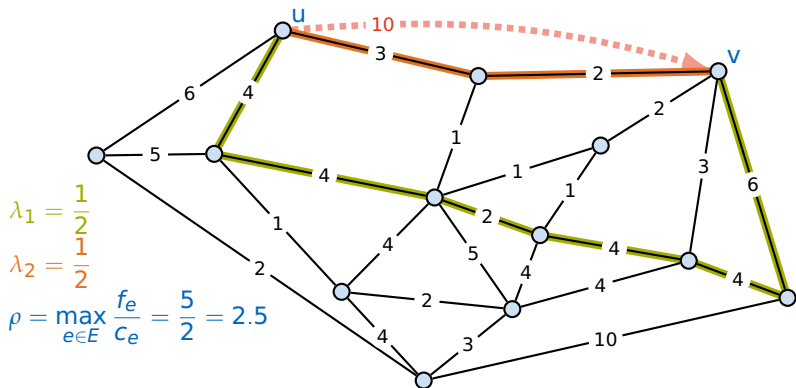
- Choose a set of spanning trees  $\{T_i\}$  of  $G$
- And a convex combination  $\lambda$  with  $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For  $e \in E$

$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$



- Choose a set of spanning trees  $\{T_i\}$  of  $G$
- And a convex combination  $\lambda$  with  $\sum_i \lambda_i = 1, \lambda \geq 0$
- Routing is now split according to this combination. For  $e \in E$

$$f(e) = \sum_{\substack{i: \\ e \in T_i}} \lambda_i D_i(e)$$



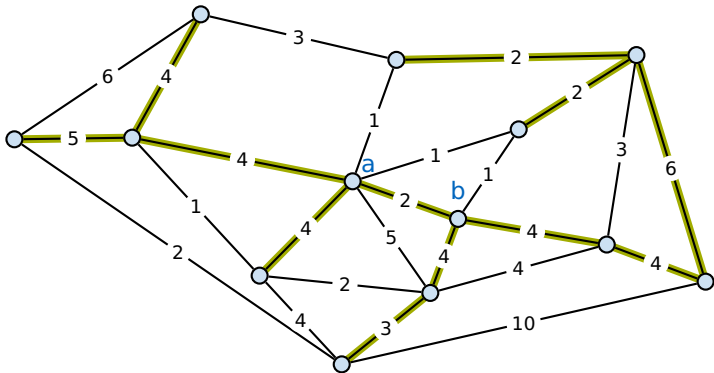
- Suppose we now find a **set of trees** such that for some  $\alpha$

$$\forall e \in E. \quad c_e \geq \frac{1}{\alpha} \sum_{\substack{i: \\ e \in T_i}} \lambda_i C_i(e)$$

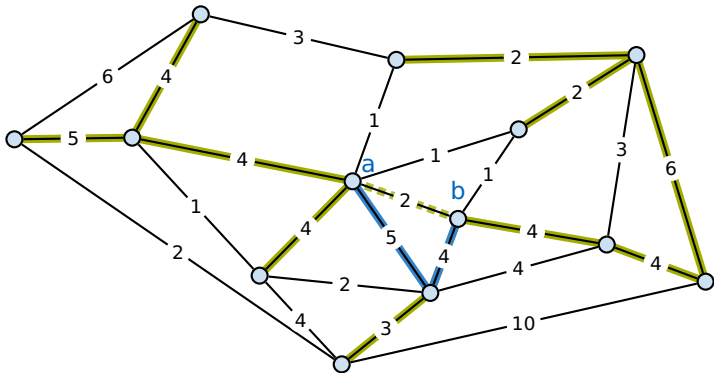
- Then we have

$$\begin{aligned} \rho &= \max_e \frac{f(e)}{c_e} \\ &= \max_e \frac{\sum_{i: e \in T_i} \lambda_i D_i(e)}{c_e} \\ &\leq \alpha \max_e \frac{\sum_{i: e \in T_i} \lambda_i D_i(e)}{\sum_{i: e \in T_i} \lambda_i C_i(e)} \\ &\leq \alpha \max_e \max_i \frac{D_i(e)}{C_i(e)} \leq \alpha \rho^* \end{aligned}$$

- Identify every edge in a tree with a **path** in  $G$
- These paths can **overlap**
- For tree  $T$  we get a mapping  $P_T : E_T \rightarrow E^+$

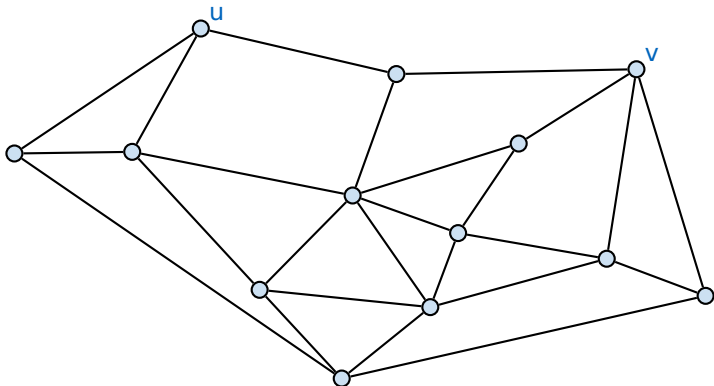


- Identify every edge in a tree with a **path** in  $G$
- These paths can **overlap**
- For tree  $T$  we get a mapping  $P_T : E_T \rightarrow E^+$



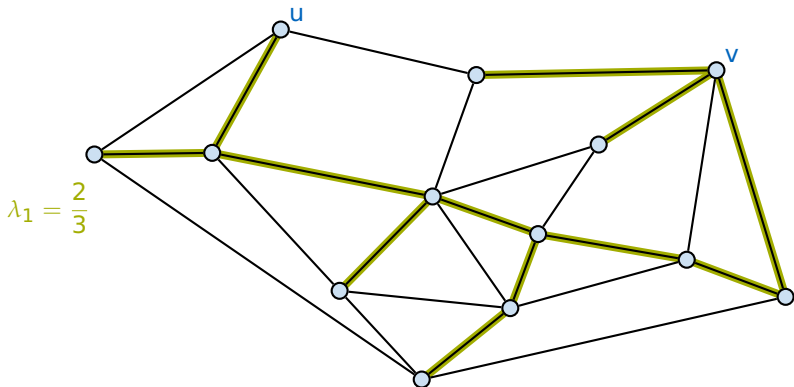
- Choose a set of pathtrees  $\{T_i\}$  of  $G$  with combination  $\lambda$
- Now route along the paths identified with edges. For  $e \in E$

$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$



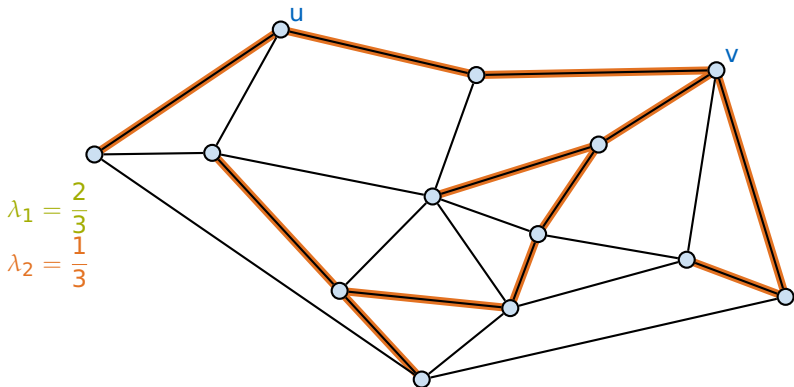
- Choose a set of pathtrees  $\{T_i\}$  of  $G$  with combination  $\lambda$
- Now route along the paths identified with edges. For  $e \in E$

$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$



- Choose a set of pathtrees  $\{T_i\}$  of  $G$  with combination  $\lambda$
- Now route along the paths identified with edges. For  $e \in E$

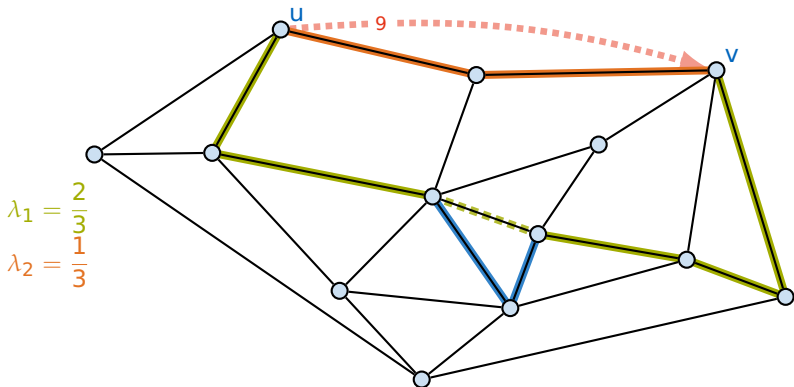
$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$





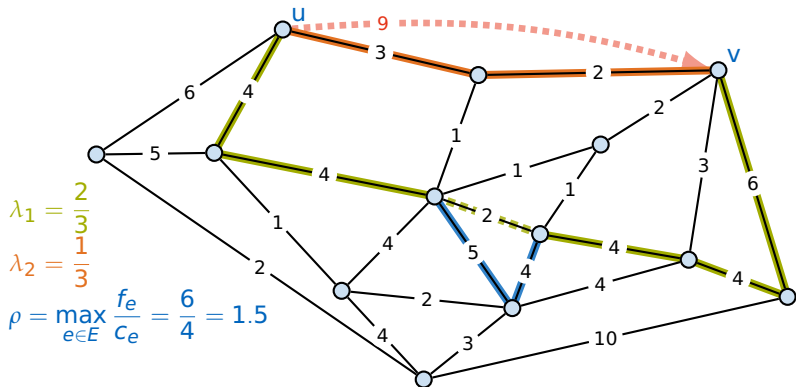
- Choose a set of pathtrees  $\{T_i\}$  of  $G$  with combination  $\lambda$
- Now route along the paths identified with edges. For  $e \in E$

$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$



- Choose a set of pathtrees  $\{T_i\}$  of  $G$  with combination  $\lambda$
- Now route along the paths identified with edges. For  $e \in E$

$$f(e) = \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)$$



- Again suppose we now find a **set of trees** such that for some  $\alpha$

$$\forall e \in E. \quad c_e \geq \frac{1}{\alpha} \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} C_i(e_T)$$

- Then we have

$$\begin{aligned} \rho &= \max_e \frac{f(e)}{c_e} \\ &\leq \alpha \max_e \frac{\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)}{\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} C_i(e_T)} \\ &\leq \alpha \max_e \max_i \frac{D_i(e)}{C_i(e)} \leq \alpha \rho^* \end{aligned}$$

- Again suppose we now find a **set of trees** such that for some  $\alpha$

$$\forall e \in E. \quad c_e \geq \frac{1}{\alpha} \sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} C_i(e_T)$$

- Then we have

$$\begin{aligned} \rho &= \max_e \frac{f(e)}{c_e} \\ &\leq \alpha \max_e \frac{\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} D_i(e_T)}{\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ e \in P_i(e_T)}} C_i(e_T)} \\ &\leq \alpha \max_e \max_i \frac{D_i(e)}{C_i(e)} \leq \alpha \rho^* \end{aligned}$$

How do we find such a set of trees? How large is  $\alpha$ ?

## Primal Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.  
 We want to find the best trees with smallest  $\alpha$ .

$$\begin{aligned}
 \min_{\alpha, \lambda} \quad & \alpha \\
 \text{s. t.} \quad & \sum_{i \in \mathcal{I}} \lambda_i \sum_{\substack{e_T \in \mathcal{I}_i: \\ (u,v) \in P_i(e_T)}} C_i(e_T) \leq \alpha C_{uv} \quad \forall u, v \in V \\
 & \sum_{i \in \mathcal{I}} \lambda_i = 1 \\
 & \lambda \geq 0
 \end{aligned}$$

We want to show that  $\alpha \in \mathcal{O}(\log n)$

## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\max_{z, \mathcal{L}} z$$

$$\text{s. t. } \sum_{u,v \in V} c_{uv} l_{uv} = 1$$

$$z \leq \sum_{e_T \in \mathcal{T}_i} c_i(e_T) \sum_{(u,v) \in P_i(e_T)} l_{uv} \quad \forall i \in \mathcal{I}$$

$$\mathcal{L} \geq 0$$

If  $z \in \mathcal{O}(\log n)$  then  $\alpha \in \mathcal{O}(\log n)$  by strong duality

## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\max_{z, \mathcal{L}} z$$

$$\text{s. t. } \sum_{u,v \in V} c_{uv} l_{uv} = 1$$

$$z \leq \sum_{e_T \in \mathcal{T}_i} C_i(e_T) \sum_{(u,v) \in P_i(e_T)} l_{uv} \quad \forall i \in \mathcal{I}$$

$$\mathcal{L} \geq 0$$

- We interpret the  $l_{uv}$  as edge lengths in  $G$
- They define a **shortest path metric**  $d_\ell(u, v)$
- For an edge  $e = (x, y)$  we write  $d_\ell(e) := d_\ell(x, y)$

## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\max_{z, \mathcal{L}} z$$

$$\text{s. t. } \sum_{u,v \in V} c_{uv} l_{uv} = 1$$

$$z \leq \sum_{e_T \in \mathcal{T}_i} c_i(e_T) \sum_{(u,v) \in P_i(e_T)} l_{uv} \quad \forall i \in \mathcal{I}$$

$$\mathcal{L} \geq 0 \quad \geq d_\ell(e_T)$$

- We interpret the  $l_{uv}$  as edge lengths in  $G$
- They define a **shortest path metric**  $d_\ell(u, v)$
- For an edge  $e = (x, y)$  we write  $d_\ell(e) := d_\ell(x, y)$



## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{z, \mathcal{L}} \quad & z \\ \text{s. t.} \quad & \sum_{u, v \in V} c_{uv} \ell_{uv} = 1 \\ & z \leq \sum_{e_T \in T_i} C_i(e_T) d_\ell(e_T) \quad \forall i \in \mathcal{I} \\ & \mathcal{L} \geq 0 \end{aligned}$$

- We interpret the  $\ell_{uv}$  as edge lengths in  $G$
- They define a **shortest path metric**  $d_\ell(u, v)$
- For an edge  $e = (x, y)$  we write  $d_\ell(e) := d_\ell(x, y)$

## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\begin{aligned}
 \max_{z, \mathcal{L}} \quad & z \\
 \text{s. t.} \quad & \sum_{u, v \in V} c_{uv} \ell_{uv} = 1 \\
 & z \leq \sum_{e_T \in T_i} c_i(e_T) d_\ell(e_T) \quad \forall i \in \mathcal{I} \\
 & \mathcal{L} \geq 0 \qquad \qquad \qquad \geq \min_{i \in \mathcal{I}} \dots
 \end{aligned}$$

- We interpret the  $\ell_{uv}$  as edge lengths in  $G$
- They define a **shortest path metric**  $d_\ell(u, v)$
- For an edge  $e = (x, y)$  we write  $d_\ell(e) := d_\ell(x, y)$

## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{z, \mathcal{L}} \quad & z \\ \text{s. t.} \quad & \sum_{u, v \in V} c_{uv} \ell_{uv} = 1 \\ & z \leq \min_{i \in \mathcal{I}} \sum_{e_T \in T_i} c_i(e_T) d_\ell(e_T) \\ & \mathcal{L} \geq 0 \end{aligned}$$

- We interpret the  $\ell_{uv}$  as edge lengths in  $G$
- They define a **shortest path metric**  $d_\ell(u, v)$
- For an edge  $e = (x, y)$  we write  $d_\ell(e) := d_\ell(x, y)$

## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{\mathcal{L}} \quad & \min_{i \in \mathcal{I}} \sum_{e_T \in T_i} C_i(e_T) d_{\ell}(e_T) \\ \text{s. t.} \quad & \sum_{u,v \in V} c_{uv} l_{uv} = 1 \\ & \mathcal{L} \geq 0 \end{aligned}$$

- Now suppose

$$\sum_{u,v \in V} c_{uv} l_{uv} = \beta > 0$$

- If we scale every length by  $\frac{1}{\beta}$  our solution will change by  $\frac{1}{\beta}$

## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{\mathcal{L}} \quad & \min_{i \in \mathcal{I}} \sum_{e_T \in T_i} C_i(e_T) d_{\ell}(e_T) \\ \text{s. t.} \quad & \sum_{u,v \in V} c_{uv} l_{uv} = 1 \\ & \mathcal{L} \geq 0 \end{aligned}$$

- Now suppose

$$\sum_{u,v \in V} c_{uv} l_{uv} = \beta > 0$$

- If we scale every length by  $\frac{1}{\beta}$  our solution will change by  $\frac{1}{\beta}$

## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{\mathcal{L}} \quad & \min_{i \in \mathcal{I}} \frac{\sum_{e_T \in \mathcal{I}_i} C_i(e_T) d_\ell(e_T)}{\sum_{u,v \in V} c_{uv} \ell_{uv}} \\ \text{s.t.} \quad & \mathcal{L} \geq 0 \end{aligned}$$

- Now suppose

$$\sum_{u,v \in V} c_{uv} \ell_{uv} = \beta > 0$$

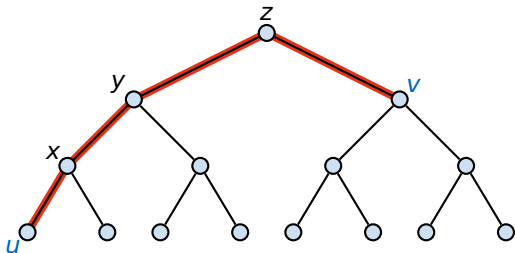
- If we scale every length by  $\frac{1}{\beta}$  our solution will change by  $\frac{1}{\beta}$

## Theorem (Tree Metric)

For our metric  $d_\ell$  there exists a *tree metric*  $(V, M)$  with

$$d_\ell(u, v) \leq M_{uv} \quad \forall u, v \in V$$

$$\sum_{u, v \in V} c_{uv} M_{uv} \leq \mathcal{O}(\log n) \sum_{u, v \in V} c_{uv} d_\ell(u, v)$$

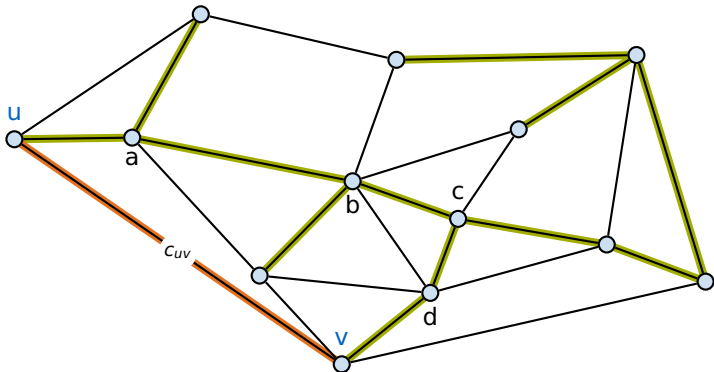


$$M_{uv} = M_{ux} + M_{xy} + M_{yz} + M_{zv}$$

## Lemma

Let  $T$  be a spanning tree and  $(V, M)$  a tree metric of  $G = (V, E)$ . Then

$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$

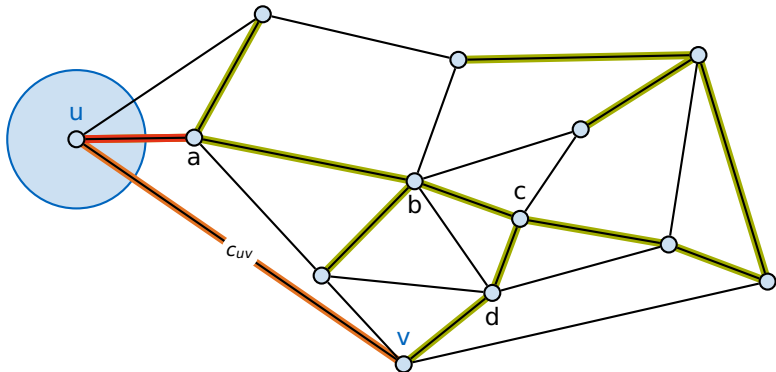




## Lemma

Let  $T$  be a spanning tree and  $(V, M)$  a tree metric of  $G = (V, E)$ . Then

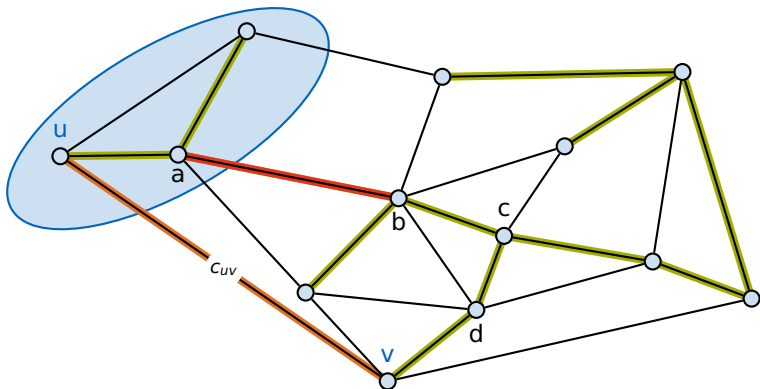
$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



## Lemma

Let  $T$  be a spanning tree and  $(V, M)$  a tree metric of  $G = (V, E)$ . Then

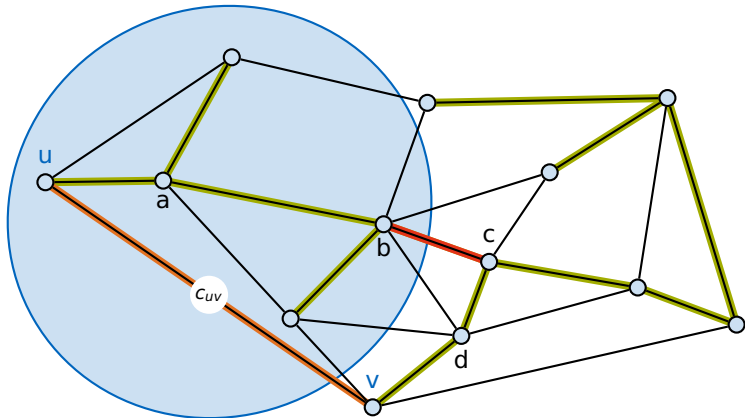
$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



## Lemma

Let  $T$  be a spanning tree and  $(V, M)$  a tree metric of  $G = (V, E)$ . Then

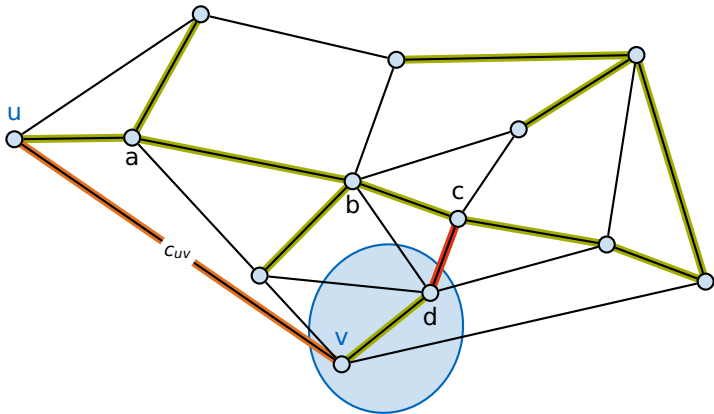
$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



## Lemma

Let  $T$  be a spanning tree and  $(V, M)$  a tree metric of  $G = (V, E)$ . Then

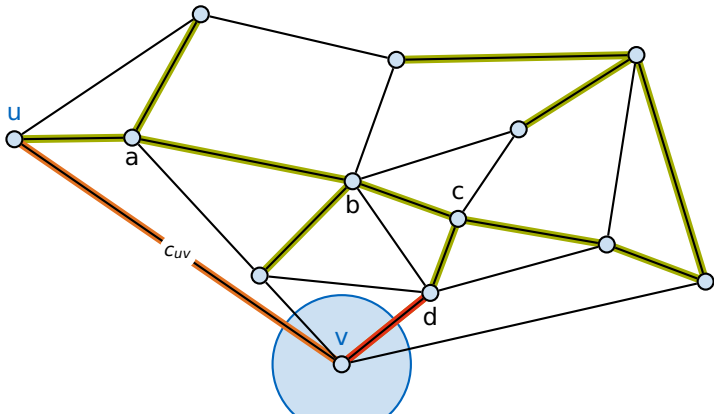
$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



## Lemma

Let  $T$  be a spanning tree and  $(V, M)$  a tree metric of  $G = (V, E)$ . Then

$$\sum_{(x,y) \in E_T} C(x,y)M_{xy} = \sum_{(u,v) \in E} c_{uv}M_{uv}$$



## Dual Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.

$$\begin{aligned} \max_{\mathcal{L}} \quad & \min_{i \in \mathcal{I}} \frac{\sum_{e_T \in T_i} C_i(e_T) d_\ell(e_T)}{\sum_{u, v \in V} c_{uv} \ell_{uv}} \\ \text{s. t.} \quad & \mathcal{L} \geq 0 \end{aligned}$$

For any  $\mathcal{L}$  we know that for the **minimizing tree**  $T_i$  holds

$$\begin{aligned} \sum_{e_T \in T_i} C_i(e_T) d_\ell(e_T) &\leq \sum_{e_T \in T_i} C_i(e_T) M_{e_T} \\ &= \sum_{u, v \in V} c_{uv} M_{uv} \\ &\leq \mathcal{O}(\log n) \sum_{u, v \in V} c_{uv} d_\ell(u, v) \\ &\leq \mathcal{O}(\log n) \sum_{u, v \in V} c_{uv} \ell_{uv} \\ \frac{\sum_{e_T \in T_i} C_i(e_T) d_\ell(e_T)}{\sum_{u, v \in V} c_{uv} \ell_{uv}} &\leq \mathcal{O}(\log n) \end{aligned}$$

## Primal Program

Let  $\mathcal{I}$  be the exponentially large set of **all pathtrees**.  
We want to find the best trees with smallest  $\alpha$ .

$$\begin{aligned}
 \min_{\alpha, \lambda} \quad & \alpha \\
 \text{s. t.} \quad & \sum_{i \in \mathcal{I}} \lambda_i \sum_{\substack{e_T \in \mathcal{I}_i: \\ (u, v) \in P_i(e_T)}} C_i(e_T) \leq \alpha C_{uv} \quad \forall u, v \in V \\
 & \sum_{i \in \mathcal{I}} \lambda_i = 1 \\
 & \lambda \geq 0
 \end{aligned}$$

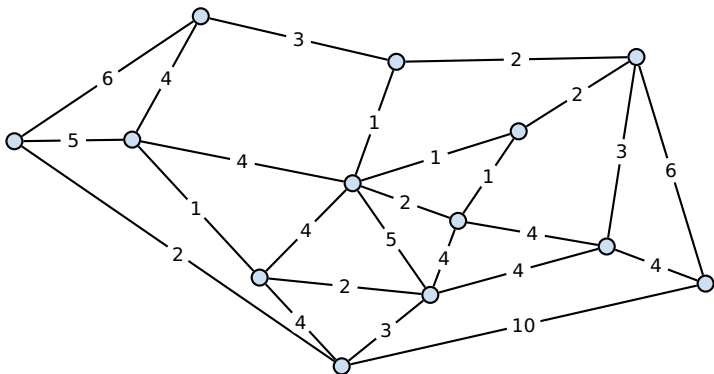
- There is a  $\lambda$  such that  $\alpha \in \mathcal{O}(\log n)$
- But why are polynomially many trees enough?
- This gives an  $\mathcal{O}(\log n)$ -approximation

## Problem (Minimum Bisection)

Given

- An undirected Graph  $G = (V, E)$
- A cost function  $c : E \rightarrow \mathbb{R}^+$

Find a set  $S \subset V$  containing half the vertices with *minimal split cost*.



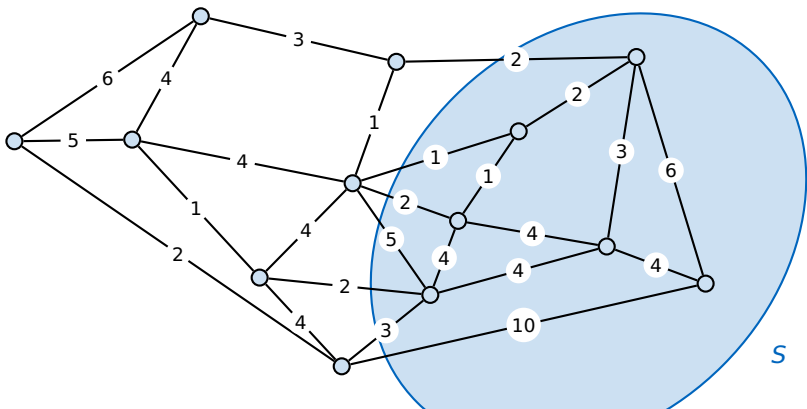


## Problem (Minimum Bisection)

Given

- An undirected Graph  $G = (V, E)$
- A cost function  $c : E \rightarrow \mathbb{R}^+$

Find a set  $S \subset V$  containing half the vertices with *minimal split cost*.

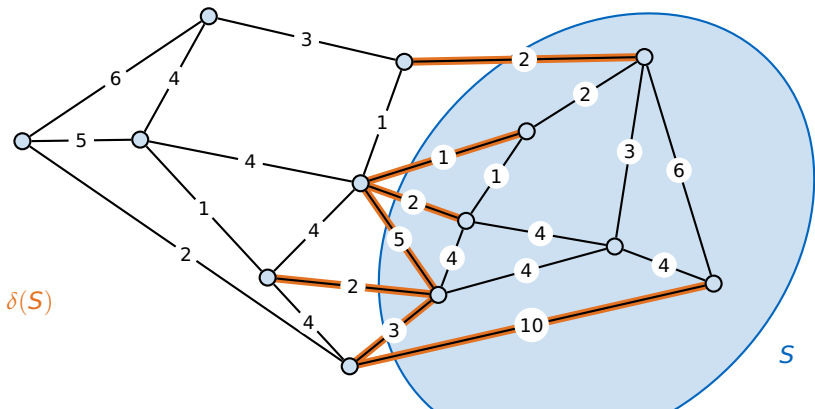


## Problem (Minimum Bisection)

Given

- An undirected Graph  $G = (V, E)$
- A cost function  $c : E \rightarrow \mathbb{R}^+$

Find a set  $S \subset V$  containing half the vertices with *minimal split cost*.

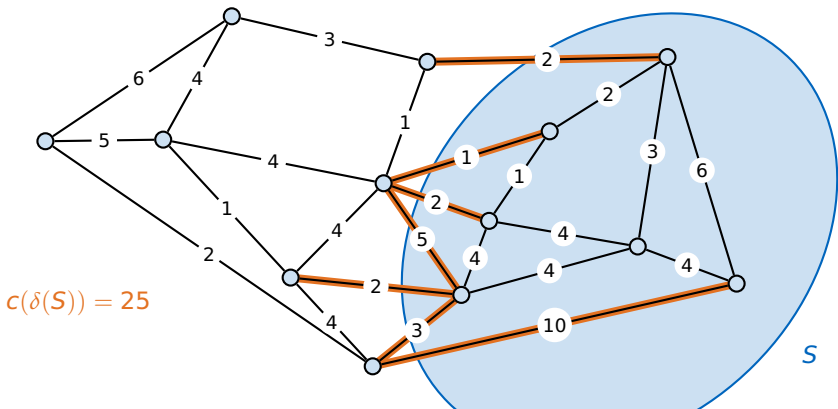


## Problem (Minimum Bisection)

Given

- An undirected Graph  $G = (V, E)$
- A cost function  $c : E \rightarrow \mathbb{R}^+$

Find a set  $S \subset V$  containing half the vertices with *minimal split cost*.



## Minimum Bisection Approximation

Given graph  $G = (V, E)$  and cost function  $c : E \rightarrow \mathbb{R}^+$ .

- 1 Interpret costs  $c(e)$  as **capacities**
- 2 Solve oblivious routing on  $G$ , obtaining **trees**  $T_i$
- 3 Find minimum **tree bisections**  $X_i$  for all trees  $T_i$
- 4 Choose the  $X_i$  with **lowest**  $c(\delta(X_i))$

We have to show

- What the  $X_i$  actually are
- An  $\mathcal{O}(\log n)$ -**approximation** guarantee
- That we can find the  $X_i$  in polynomial time

## Minimum Bisection Approximation

Given graph  $G = (V, E)$  and cost function  $c : E \rightarrow \mathbb{R}^+$ .

- 1 Interpret costs  $c(e)$  as **capacities**
- 2 Solve oblivious routing on  $G$ , obtaining **trees**  $T_i$
- 3 Find minimum **tree bisections**  $X_i$  for all trees  $T_i$
- 4 Choose the  $X_i$  with **lowest**  $c(\delta(X_i))$

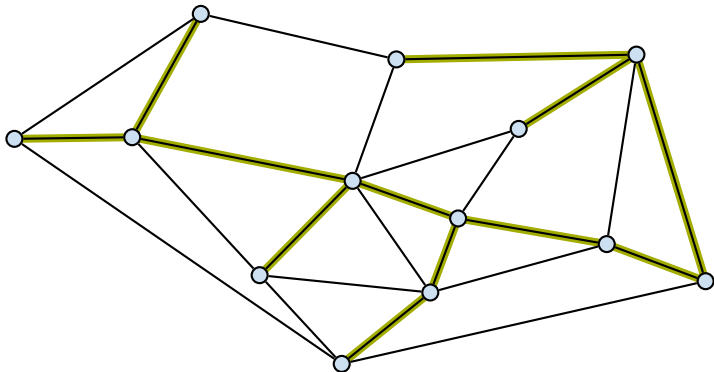
We have to show

- What the  $X_i$  actually are
- An  $\mathcal{O}(\log n)$ -**approximation** guarantee
- That we can find the  $X_i$  in polynomial time

- Given a spanning tree  $T$  of  $G$  with an edge  $e_T \in E_T$
- Define a new **cost function**  $c_T$  using tree splits

$$c_T(e_T) = C(e_T)$$

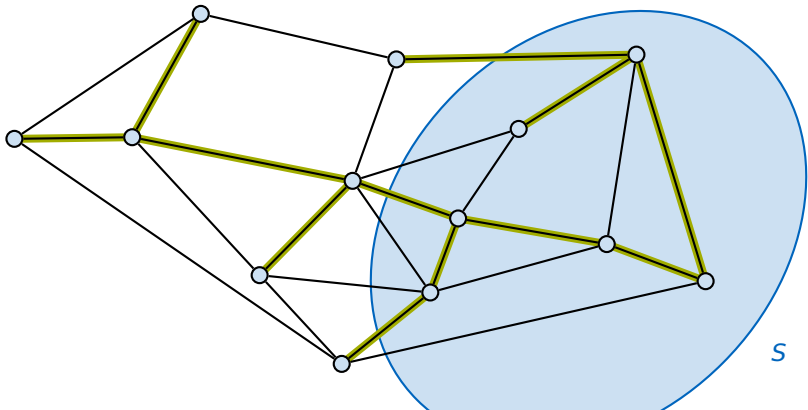
$$c_T(\delta(S)) = \sum_{\substack{e_T \in E_T: \\ e_T \in \delta(S)}} C(e_T)$$



- Given a spanning tree  $T$  of  $G$  with an edge  $e_T \in E_T$
- Define a new **cost function**  $c_T$  using tree splits

$$c_T(e_T) = C(e_T)$$

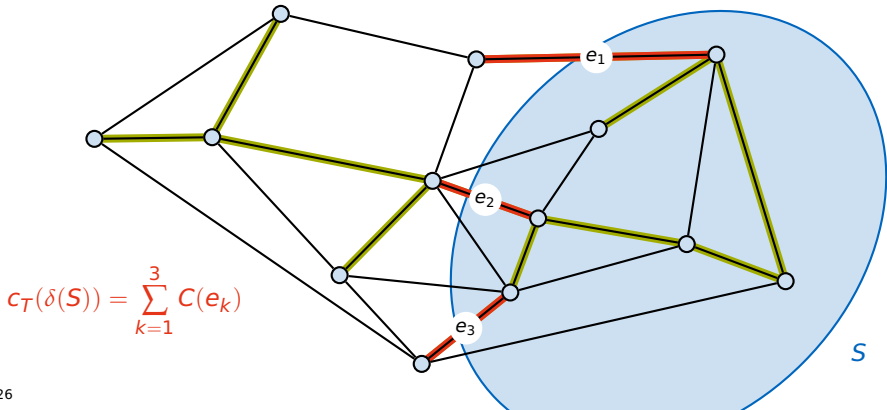
$$c_T(\delta(S)) = \sum_{\substack{e_T \in E_T: \\ e_T \in \delta(S)}} C(e_T)$$



- Given a spanning tree  $T$  of  $G$  with an edge  $e_T \in E_T$
- Define a new **cost function**  $c_T$  using tree splits

$$c_T(e_T) = C(e_T)$$

$$c_T(\delta(S)) = \sum_{\substack{e_T \in E_T: \\ e_T \in \delta(S)}} C(e_T)$$

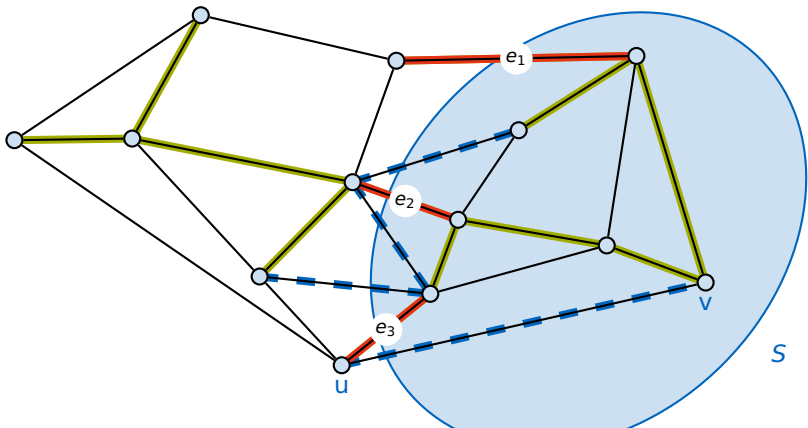




## Lemma

For any spanning tree  $T$  and any  $S \subseteq V$  we have

$$c(\delta(S)) \leq c_T(\delta(S))$$



## Lemma

Let  $\{T_i\}$  be a solution to the *oblivious flow* problem on  $G$ .  
Then for any  $S \subseteq V$  we have

$$\sum_i \lambda_i c_{T_i}(\delta(S)) \leq \mathcal{O}(\log n) c(\delta(S))$$

- Remember from the primal program that for all  $u, v \in V$

$$\sum_i \lambda_i \sum_{\substack{e_T \in T_i: \\ (u,v) \in P_i(e_T)}} C_i(e_T) \leq \mathcal{O}(\log n) c_{uv}$$

- We sum up the inequalities for all  $(u, v) \in \delta(S)$

## Lemma

Let  $\{T_i\}$  be a solution to the *oblivious flow* problem on  $G$ .  
Then for any  $S \subseteq V$  we have

$$\sum_i \lambda_i c_{T_i}(\delta(S)) \leq \mathcal{O}(\log n) c(\delta(S))$$

- We sum up the inequalities for all  $(u, v) \in \delta(S)$
- This gives us

$$\sum_i \lambda_i \sum_{(u,v) \in \delta(S)} \sum_{\substack{e_T \in T_i: \\ (u,v) \in P_i(e_T)}} C_i(e_T) \leq \mathcal{O}(\log n) c(\delta(S))$$

- We are done with the observation that

$$c_{T_i}(\delta(S)) = \sum_{\substack{e_T \in E_{T_i}: \\ e_T \in \delta(S)}} C_i(e_T) \leq \sum_{(u,v) \in \delta(S)} \sum_{\substack{e_T \in T_i: \\ (u,v) \in P_i(e_T)}} C_i(e_T)$$

## Minimum Bisection Approximation

Given graph  $G = (V, E)$  and cost function  $c : E \rightarrow \mathbb{R}^+$ .

- 1 Interpret costs  $c(e)$  as **capacities**
- 2 Solve oblivious routing on  $G$ , obtaining **trees**  $T_i$
- 3 Find minimum **tree bisections**  $X_i$  for all trees  $T_i$
- 4 Choose the  $X_i$  with **lowest**  $c(\delta(X_i))$

- Let now  $X^*, X_i$  be the optimal solutions on  $G$  and the  $T_i$ . Then

$$\begin{aligned} \sum_i \lambda_i c(\delta(X_i)) &\leq \sum_i \lambda_i c_{T_i}(\delta(X_i)) \\ &\leq \sum_i \lambda_i c_{T_i}(\delta(X^*)) \\ &\leq \mathcal{O}(\log n) c(\delta(X^*)) \end{aligned}$$

- This also holds for the **best**  $X_i$ , giving an  $\mathcal{O}(\log n)$ -**approximation**
- How to find the  $X_i$ ?